

DST-NUC980EVB User Manual

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1 OVERVIEW

This document provides a quick start guide for the DST-NUC980EVB Development Board. Users can understand both software and hardware configurations for the DST-NUC980EVB. The platform provides Linux OS and plenty of industrial control protocol for users to implement the Ethernet control applications in a very short time.

The DST-NUC980EVB board uses NUC980DR61YC microprocessor run up to 300 MHz with built-in 64MB DDR2 memory, 16 KB I-cache, 16 KB D-cache and MMU, 16 KB embedded SRAM and 16.5 KB IBR (Internal Boot ROM) for system booting from USB and SPI flash, all functions of the NUC980DR61YC are placed on the board, including peripheral interfaces such as SPI Flash memory, UART, 10/100 Mb Ethernet MAC controller, high speed USB (Device, Host), JTAG, RS485 and CAN transceiver controller. Users can use it to develop and verify applications to emulate the real behavior.

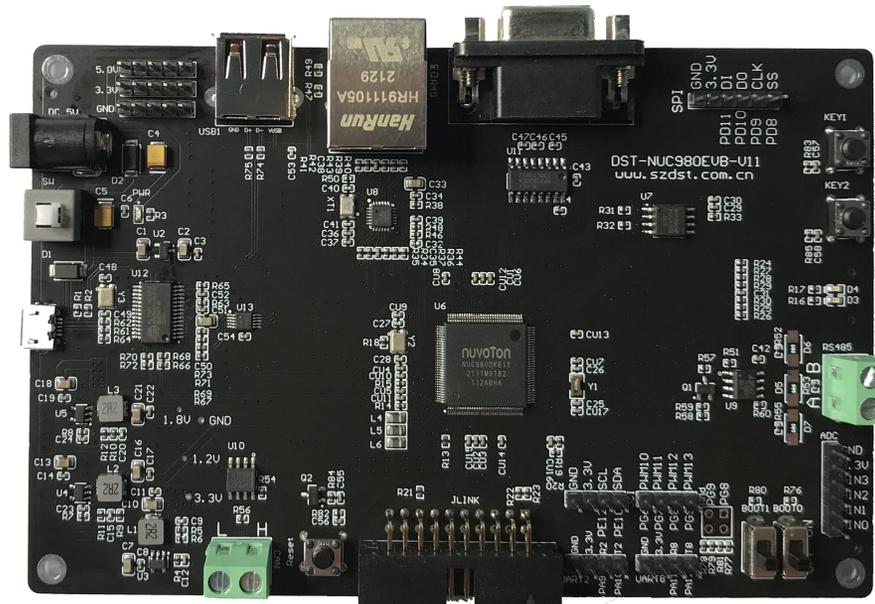


Figure 1-1 DST-NUC980EVB Development Board

2 FEATURES

- NUC980DR61YC: LQFP64 pin MCP package with DDR2 (64 MB), which can run up to 300MHz operating speed
- SPI Flash: Normal mode system booting or data storage, use W25Q128JV SPI-NOR (128M-Bit)
- Peripheral interface connector, including UART, SPI, I2C
- JTAG interface provided for software development
- RJ45 port (Ethernet0) connector
- UART8-RS485 header with transceiver controller interface
- CAN3 header with transceiver controller interface
- 2 sets of LED for status indication
- 1 sets of user-configurable push button keys
- 1 sets of system-reset push button keys
- 3.3V I/O power, 1.8V Memory power and 1.2V core power

3 HARDWARE CONFIGURATION

3.1 Front View

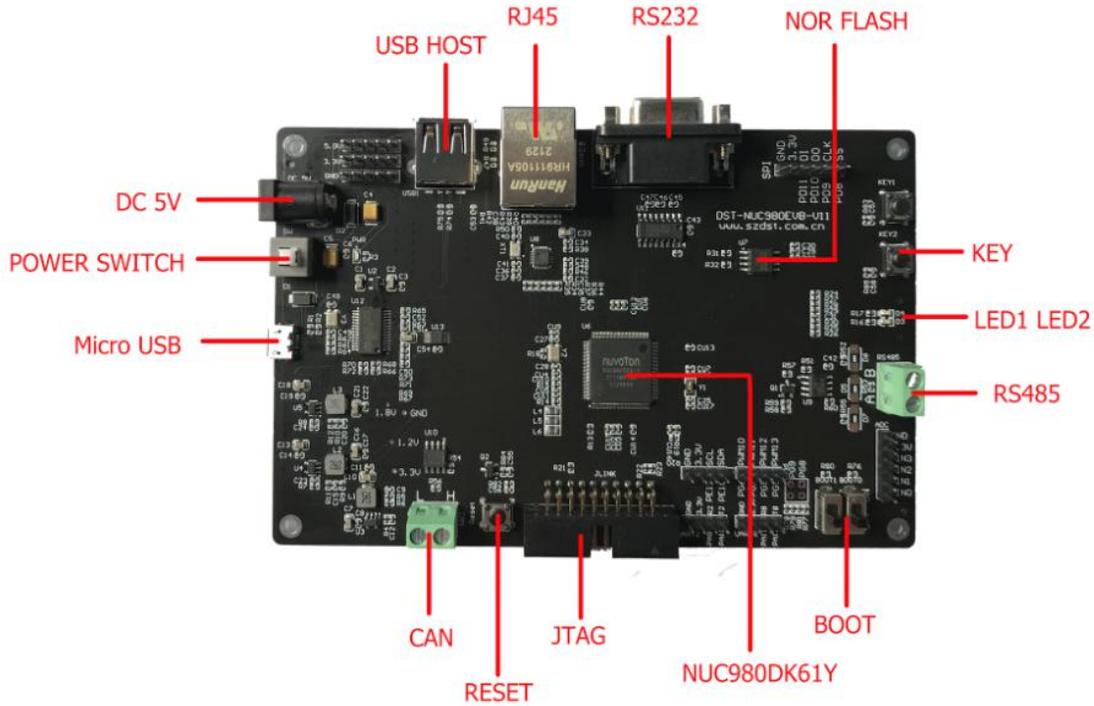


Figure 3-1 Front View of DST-NUC980EVB

Figure 3-1 shows the main components from the front view of DST-NUC980EVB Development Board

- +5V In : Power 5V input

Power Model	USB	DC 5V
Model 1	Connect to PC	-
Model 3	-	VDD5V Input

- System Reset : System will be reset if the RESET button is pressed

- User indication LEDs (LED1, LED2):

LED	Color	GPIO pin of NUC980
LED1	Green	PC11
LED2	Green	PC3

- SPI NOR Flash (U5): Use Winbond W25Q128JV 128M Bit (U5) for system booting, supporting normal mode
- JTAG interface

Connector	GPIO pin of NUC980	Function
JLINK.1	-	VDD33
JLINK.2	GPA6	nTRST
JLINK.3	GPA5	TDI
JLINK.4	GPA4	TMS
JLINK.5	GPA3	TCK
JLINK.6	GPA2	TDO
JLINK.7	-	nRESET
JLINK.8	-	VSS

- User Key SW (KEY1)

Key	GPIO pin of NUC980
K1	GPC15

- BOOT setting

Switch	Status	Function	GPIO pin of NUC980
BOOT0	ON/ON	Boot from USB	GPG1/GPG0
BOOT1	OFF/OFF	Boot from QSPI0 Flash	GPG1/GPG0

- CAN (JP2, U7): SN65HVD230 transceiver controller of CAN(U10), CAN header connect to device for communication
- Peripheral user interface(P1)

- SOC CPU: NUC980DR61YC (U6)

4 QUICK START

4.1 BSP Download

The burning tool requires a NuWriter driver to be installed on PC first. Please follow the steps below to install the driver.

Please visit nuvoTon's NuMicro™ website <https://www.nuvoton.com/products/iot-solution/iot-platform/numaker-server-nuc980/?group=Software&tab=2>) to download the "NUC980_Linux-4.4_BSP_v1.02.001". Run the "WinUSB4NuVCOM.exe" before the USB cable is plugged in. The "WinUSB4NuVCOM.exe" can be found in the "Tool" directory. Power on the NUC980 Series MPU EVB and plug the USB cable into PC, the Windows shall find a new device and then request to install its driver. Simply follow the installation and optional steps to install USB Driver, included VCOM driver.

4.2 Driver Installation

The programming tool requires a Nuvoton USB driver to be installed on PC first. Please follow the steps below to install the WinUSB driver.

Run the "WinUSB4NuVCOM.exe" before the USB cable is plugged in. The "WinUSB4NuVCOM.exe" can be found in the "Tool" directory. Power on the NUC980 Series MPU EVB and plug the USB cable into PC, the Windows shall find a new device and request to install the driver.

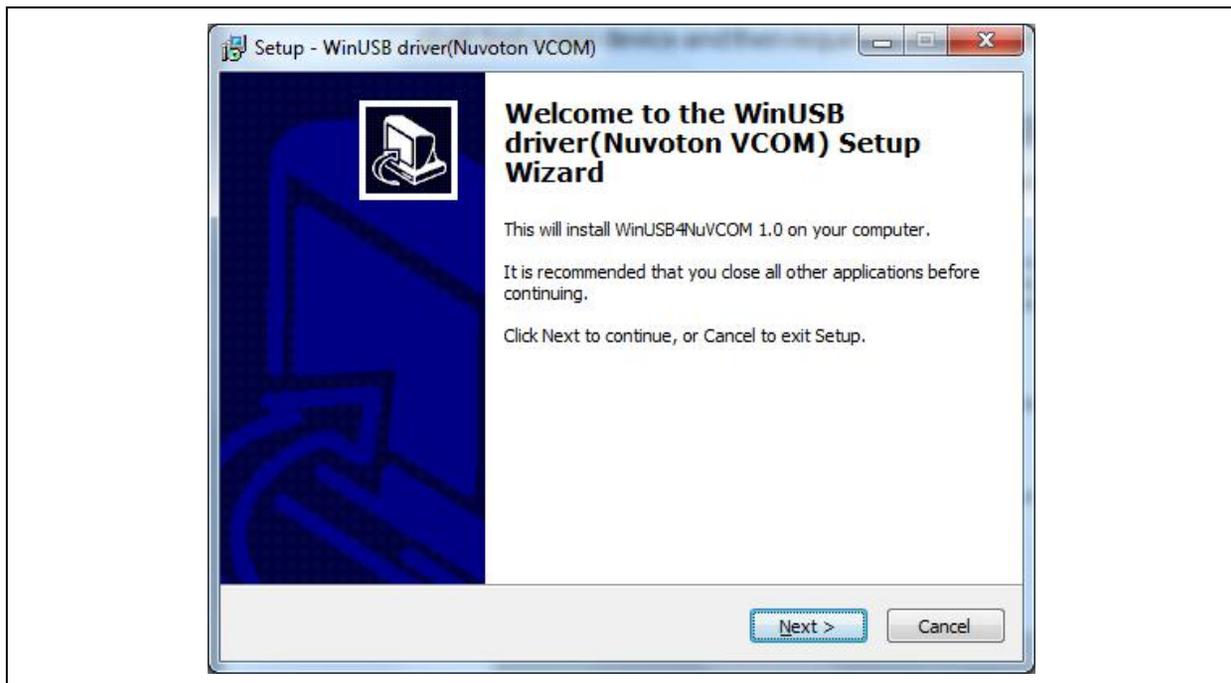
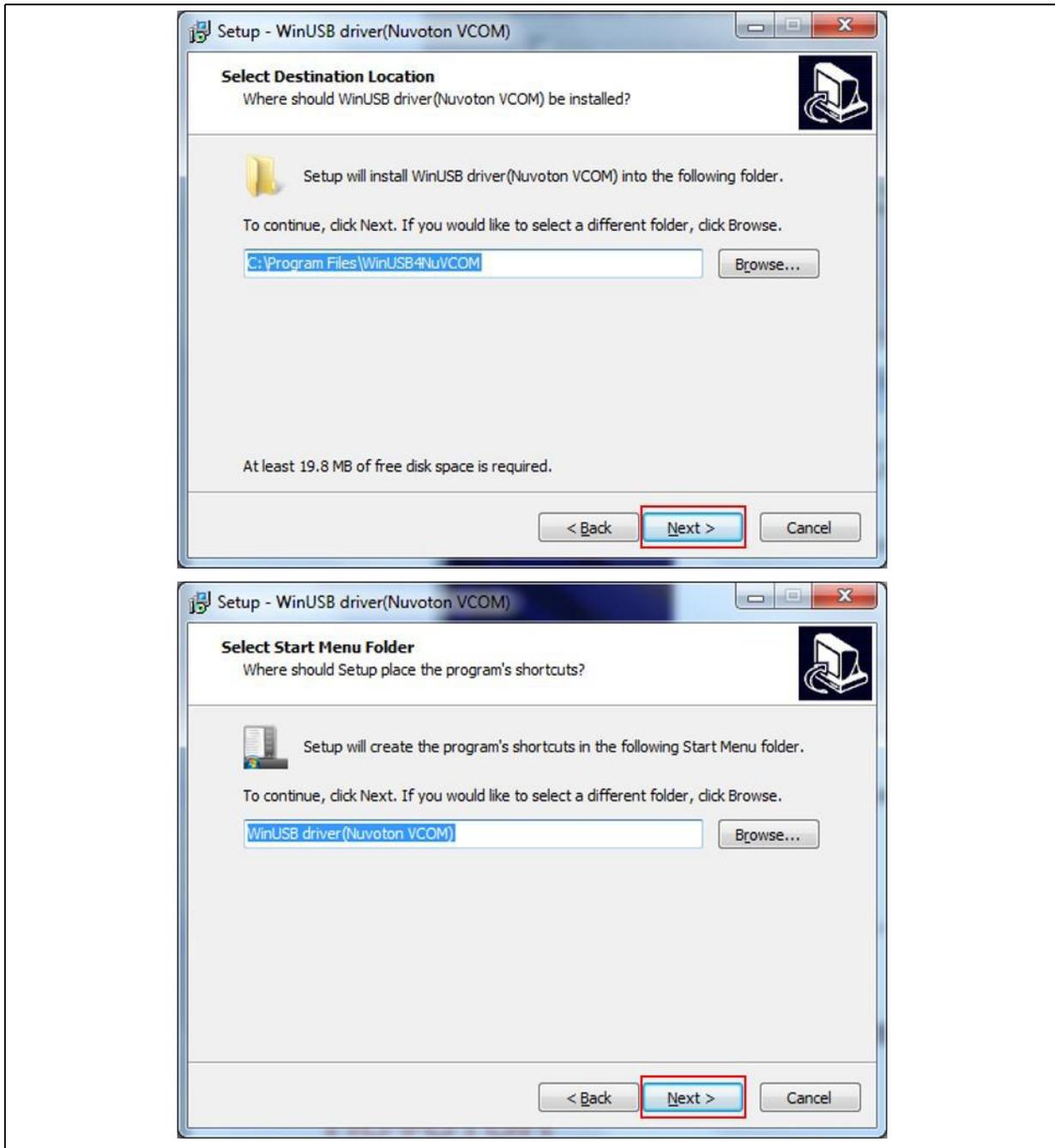


Figure 4-1 Nuvoton USB Driver Installation Setup

Click "Next". The WinUSB driver Setup Wizard will be started.



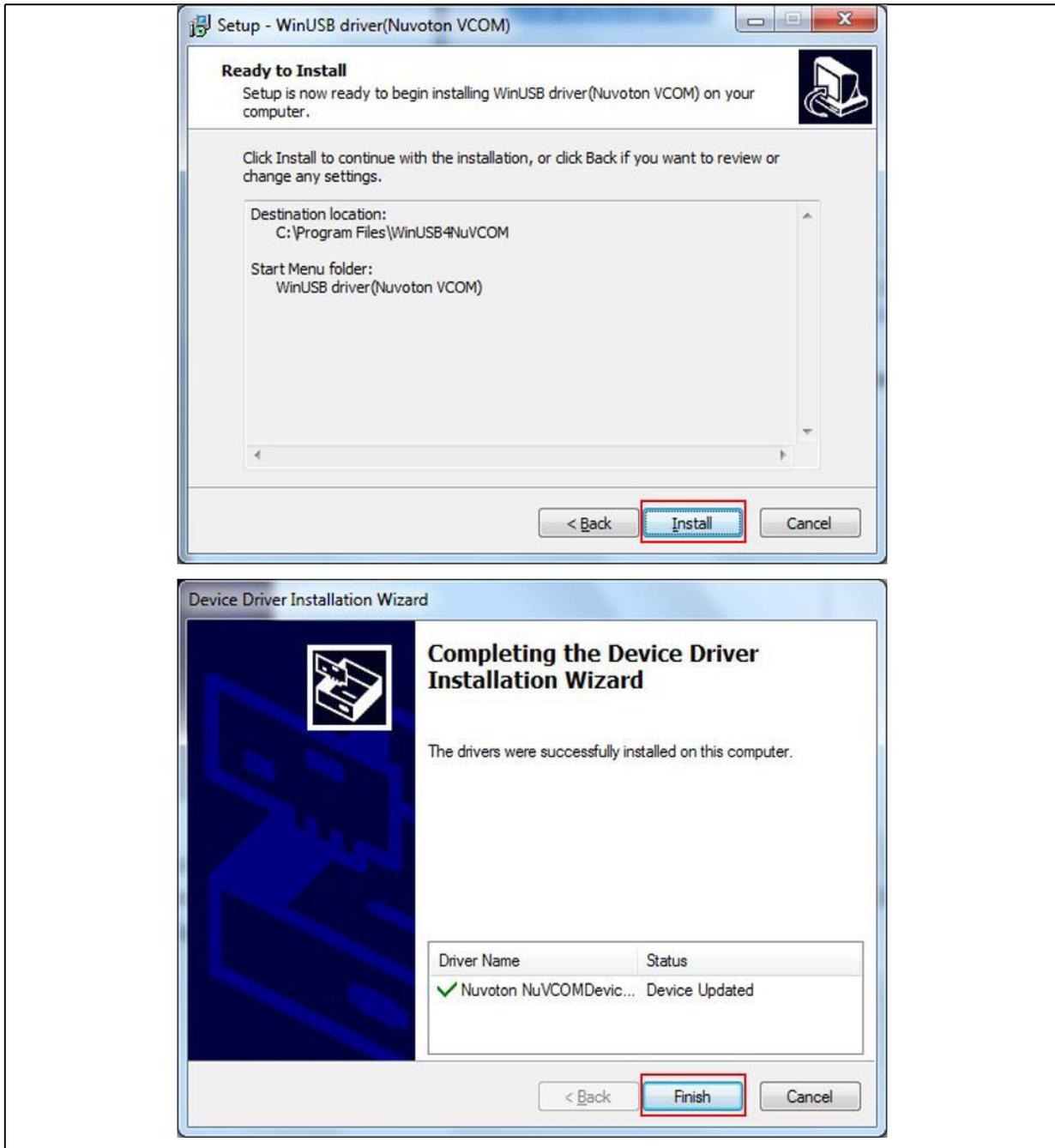


Figure 4-2 Nuvoton USB Driver Installation

The USB serial port function is used to print some messages on PC API, such as SecureCRT, through the standard UART protocol to help user to debug program.

4.3 Hardware Setting

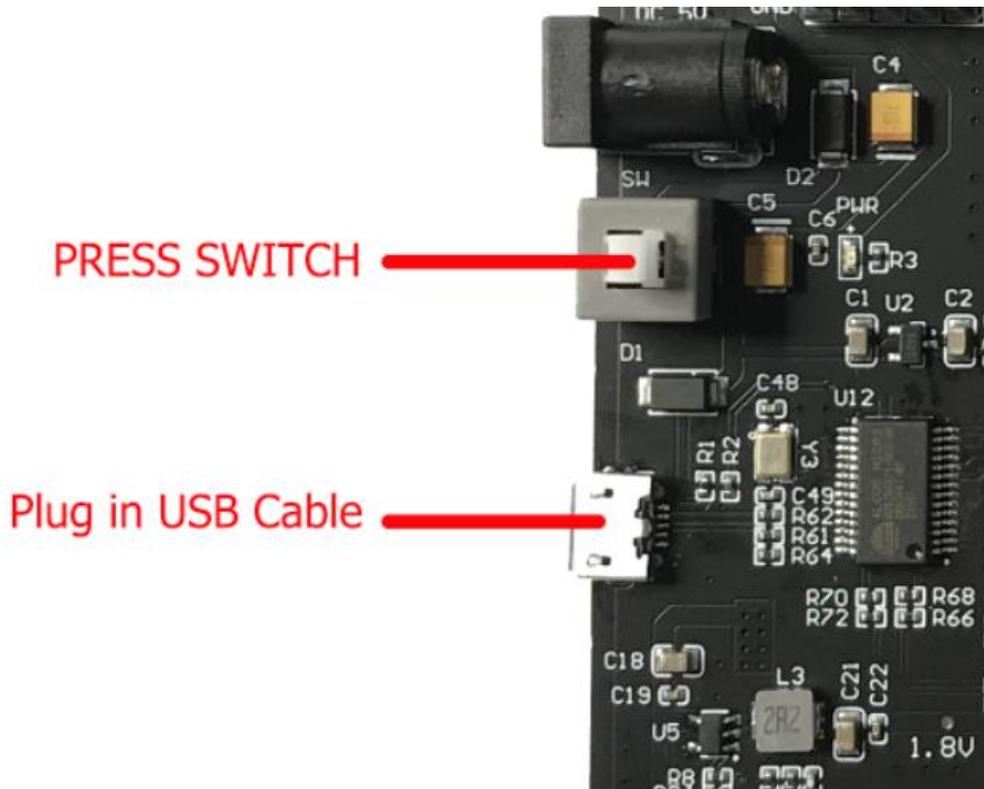


Figure 4-3 Hardware Setting

1. DST-NUC980EVB provides BOOT0, BOOT1 to select boot-up conditions. The BOOT0 and BOOT1 ON to select USB ISP mode.

Switch	Status	Function	GPIO pin of NUC980
BOOT0	ON/ON	Boot from USB	GPG1/GPG0
BOOT1	OFF/OFF	Boot from QSPI0 Flash	GPG1/GPG0

Table 4-1 Power On Setting

2. Plug in the USB cable
If the installation is successful, a virtual COM port can be found in the “Device Manager”.

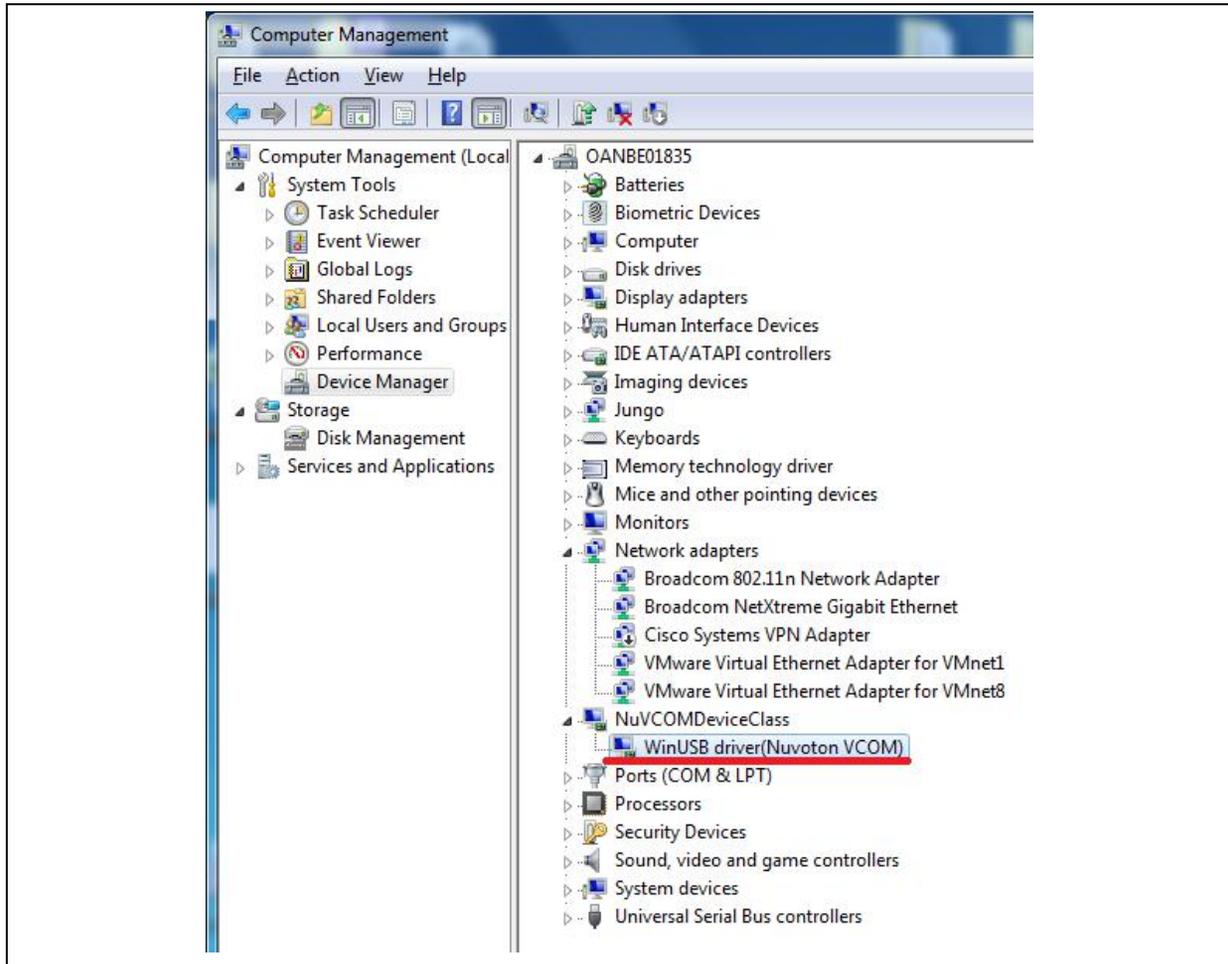


Figure 4-4 Nuvoton VCOM

4.4 Programing Kernel and U-Boot to SPI NAND Flash

1. Install NuWriter Driver. (Please refer to “**NUC980 NuWriter User Manual**”)
2. Set SW1(Power On Setting) to Boot from USB(shown in Table 4-1 and Figure 4-3). Connect USB0 to PC and connect UART console to PC.
3. Double click “**NuWriter.exe**” on PC. Select target chip as “NUC980 series” and select DDR parameter is “NUC980DR61YC.ini”. And then, press “**Continue**” button.

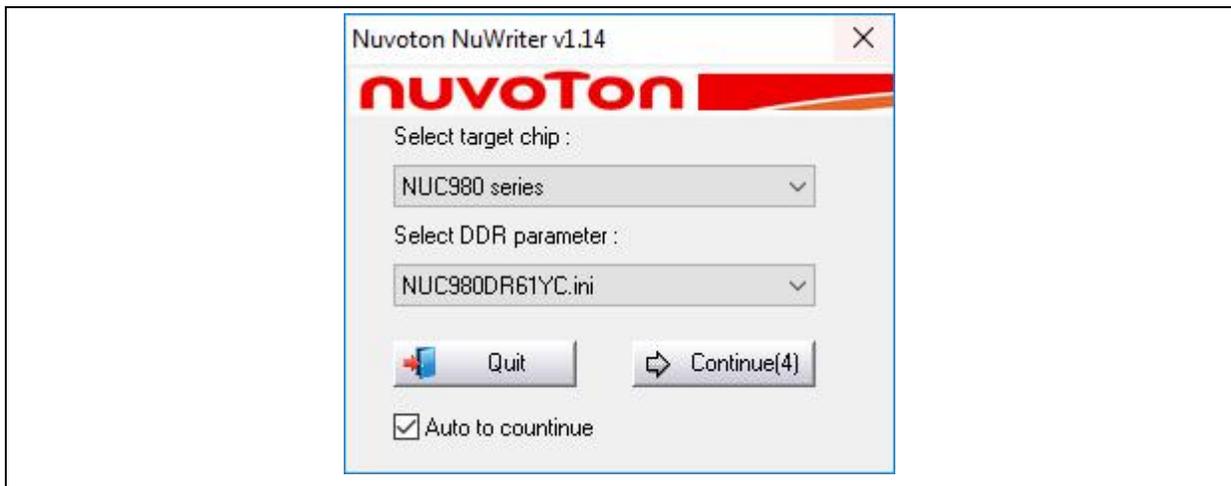


Figure 4-5 NuWriter Setting

4. According to Figure 4-6, following the steps below to program u-boot.bin:
 - a. Select the “**SPI**” type.
 - b. Fill in the image information:
 - Image Name: u-boot.bin
 - Image Type: Loader
 - Image execute address: 0xe00000
 - c. Click “**Program**”.
 - d. Waiting for the progress bar to be finished.
 - e. After “**Program**” the image, click the “**Verify**” button to read back the image data to make sure the burning status.

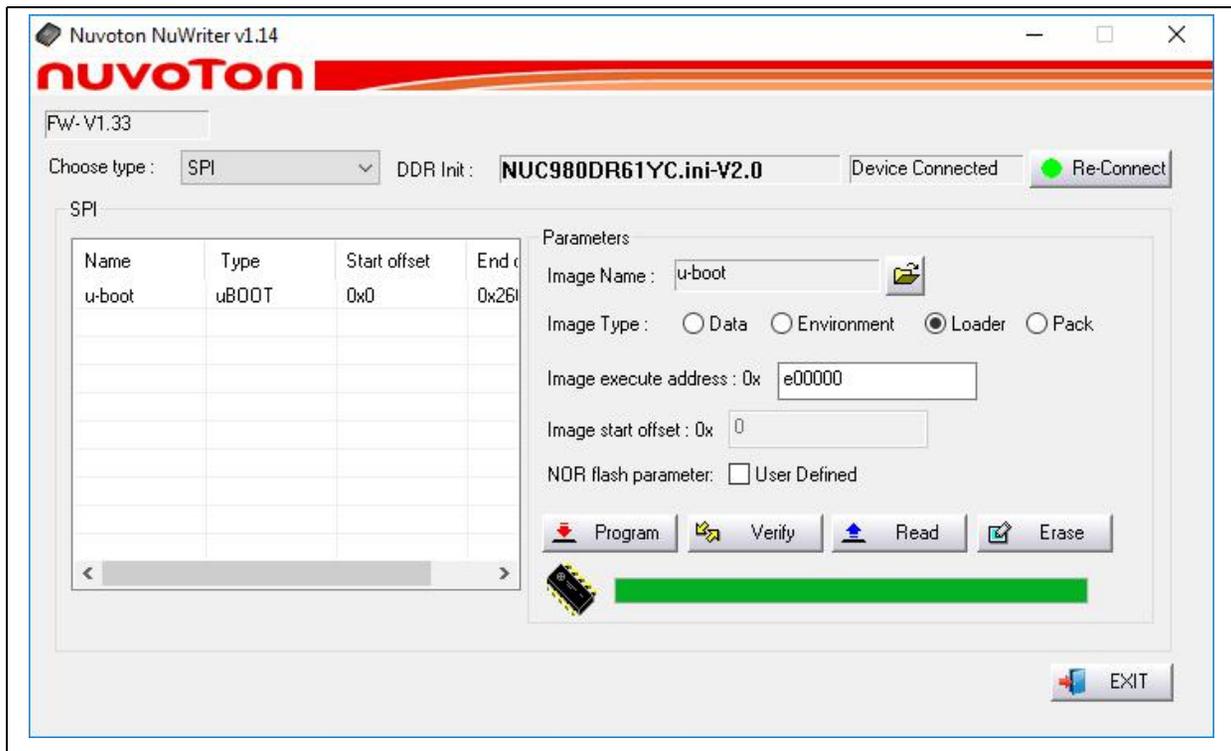


Figure 4-6 Program u-boot

5. According to Figure 4-7, following the steps to program kernel image:
 - a. Select the "SPI" type.
 - b. Fill in the image information:
 - Image Name: uimage
 - Image Type: Data
 - Image execute address: 0x200000
 - c. Click "Program".
 - d. Waiting the progress bar to be finished.
 - e. After "Program" the image, click the "Verify" button to read back the image data to make sure the burning status.

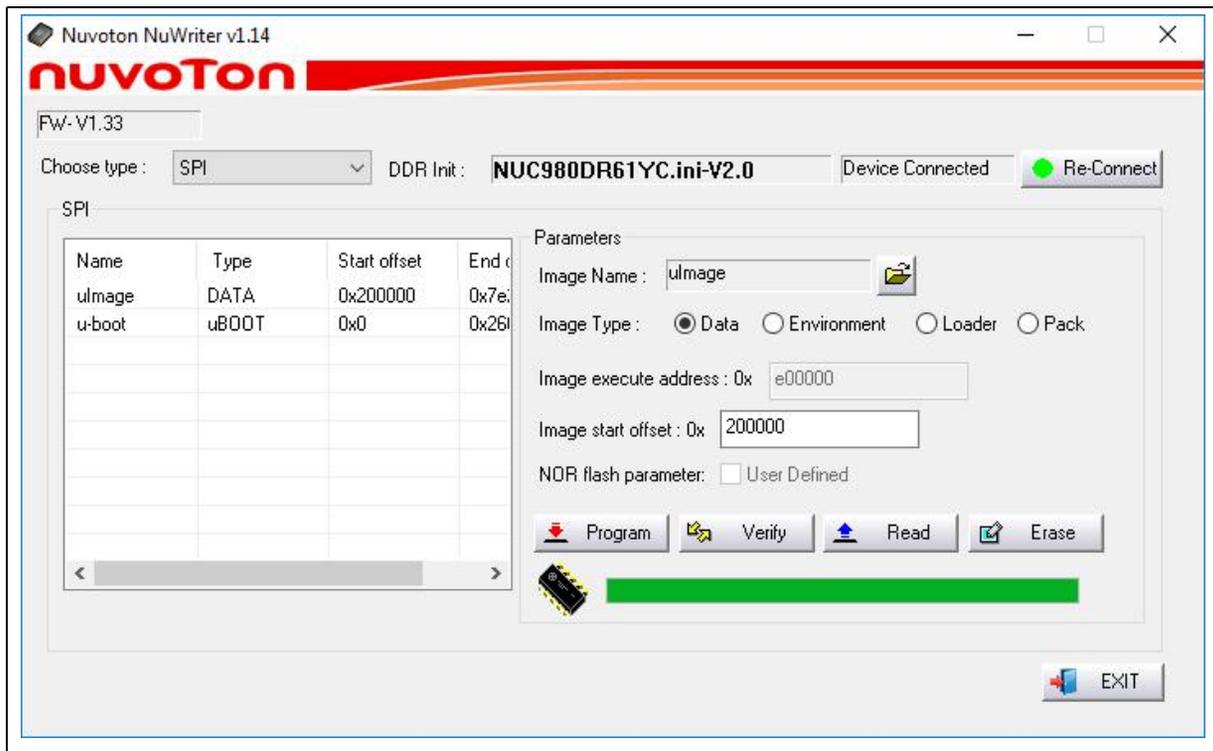


Figure 4-7 Program uimage

6. According to Figure 4-8, following the steps below to program environment:
 - a. Select the "SPI" type.
 - b. Fill in the image information:
 - Image Name: env.txt
 - Image Type: environment
 - Image start offset address: 0x80000
 - c. Click "Program".
 - d. Waiting for the progress bar to be finished.
 - e. After "Program" the image, click the "Verify" button to read back the image data to make sure the burning status.

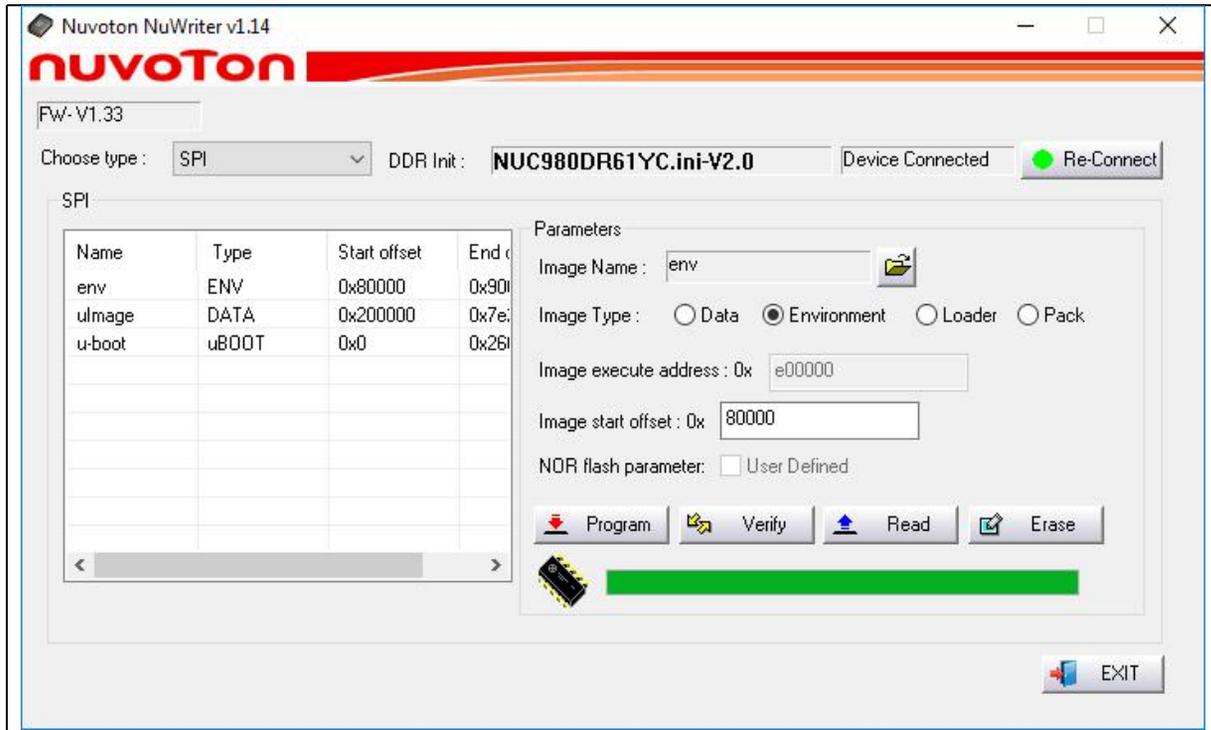


Figure 4-8 Program environment

For more details about NuWriter tool, please refer to “**NUC980 NuWriter User Manual**” in the “Documents” directory.

For more details about kernel image and uboot, please refer to “**NUC980_970 Linux environment on VMware User Manual**” from Nuvoton website.

URL: <https://www.nuvoton.com/products/iot-solution/iot-platform/numaker-server-nuc980/?group=Document&tab=2>

5 BLOCK DIAGRAM SCHEMATIC

5.1 GPIO List Schematic

PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
PA0	CAN3_RXD	PE4	I2C1_SCL	PC3	LED_G	PD2	QSPI0_SS0	PE11	USB0_VBUSVLD	PF0	RMII1_RXERR	PG0	CFG[0]
PA1	CAN3_TXD	PE6	I2C1_SDA	PC4	SPI0_DO	PD3	QSPI0_CLK			PF1	RMII1_CRSDV	PG1	CFG[1]
PA2	JTAG1_TDO			PC5	SPI0_SS0	PD4	QSPI0_DO			PF2	RMII1_RXD1		
PA3	JTAG1_TCK			PC6	SPI0_CLK	PD5	QSPI0_DI			PF3	RMII1_RXD0		
PA4	JTAG1_TMS			PC8	SPI0_DI					PF4	RMII1_REFCLK		
PA5	JTAG1_TDI			PC9	UART4_TWD					PF5	RMII1_TXEN		
PA6	JTAG1_nTRST			PC10	UART4_RXD					PF6	RMII1_TXD1		
				PC11	LED_G					PF7	RMII1_TXD0		
				PC12	UART8_TWD					PF8	RMII1_MDIO		
				PC13	UART8_RXD					PF9	RMII1_MDC		
				PC14	UART8_RTS					PF11	UART0_RXD		
				PC15	button					PF12	UART0_TXD		

Figure 5-1 GPIO List Schematic

5.3 NUC980DK Schematic

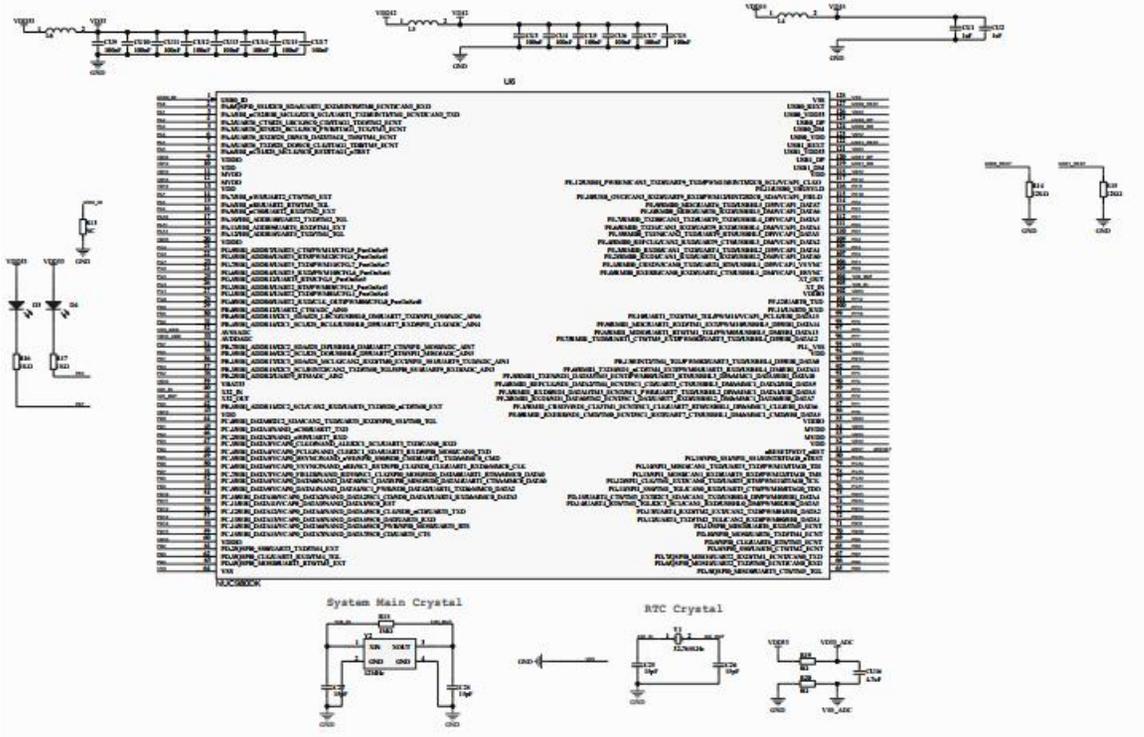


Figure 5-3 NUC980DK Schematic

5.5 Configure Schematic

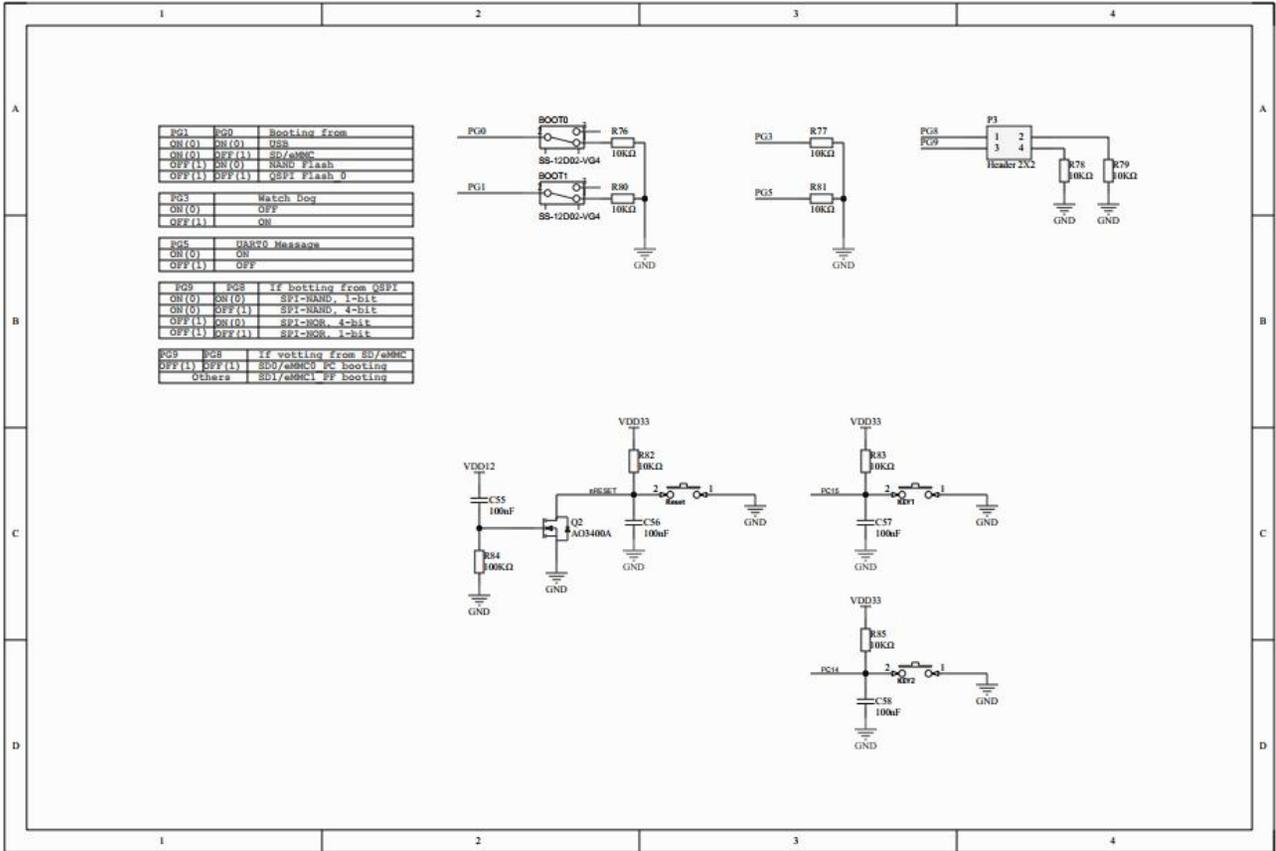


Figure 5-5 Configure Schematic

5.6 PORT Schematic

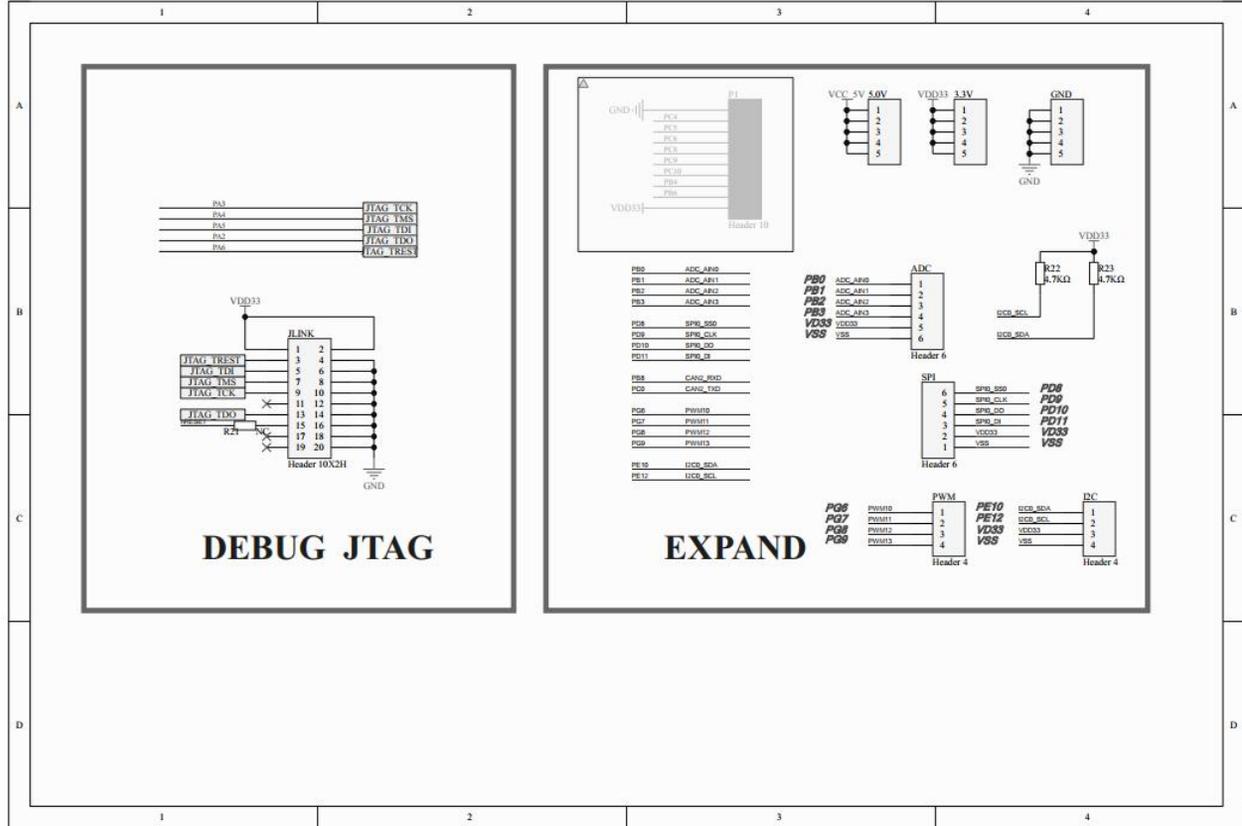


Figure 5-6 PORT Schematic

5.7 Memory Schematic

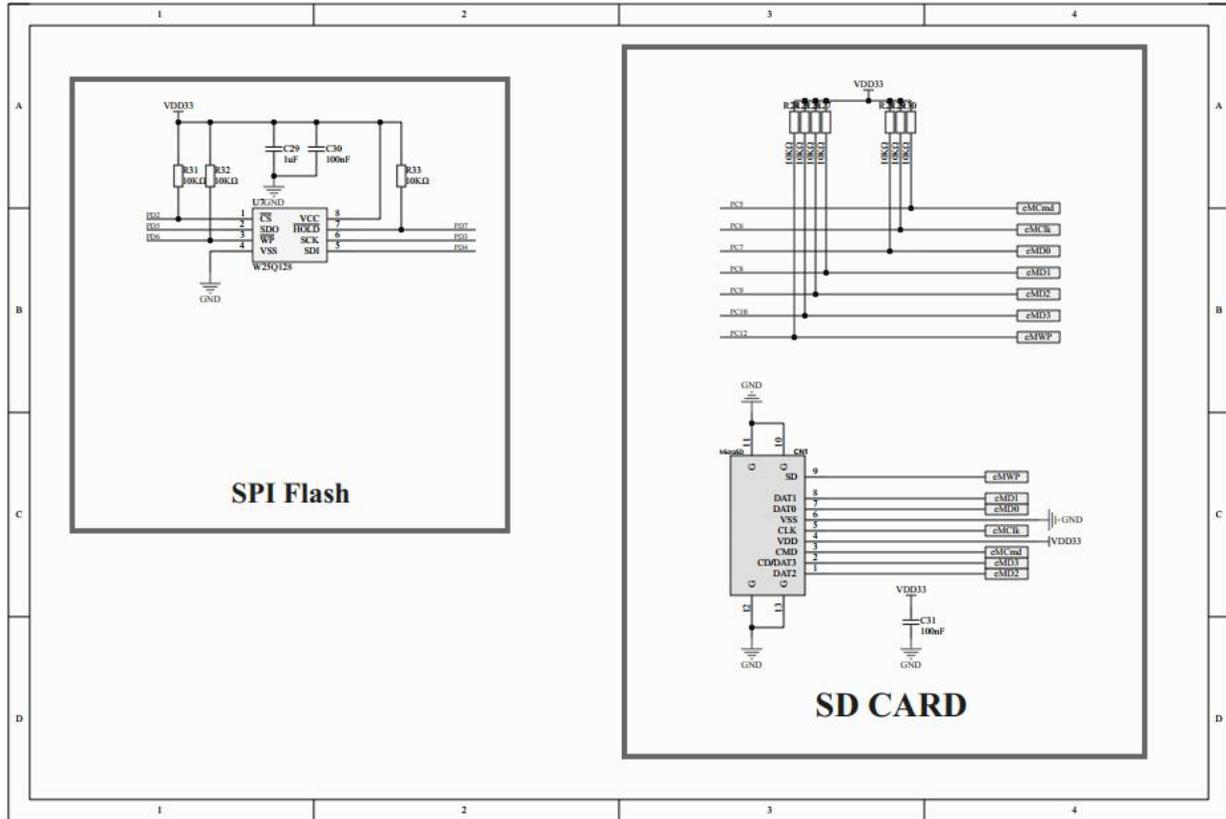


Figure 5-7 Memory Schematic

5.8 Ethernet connector Schematic

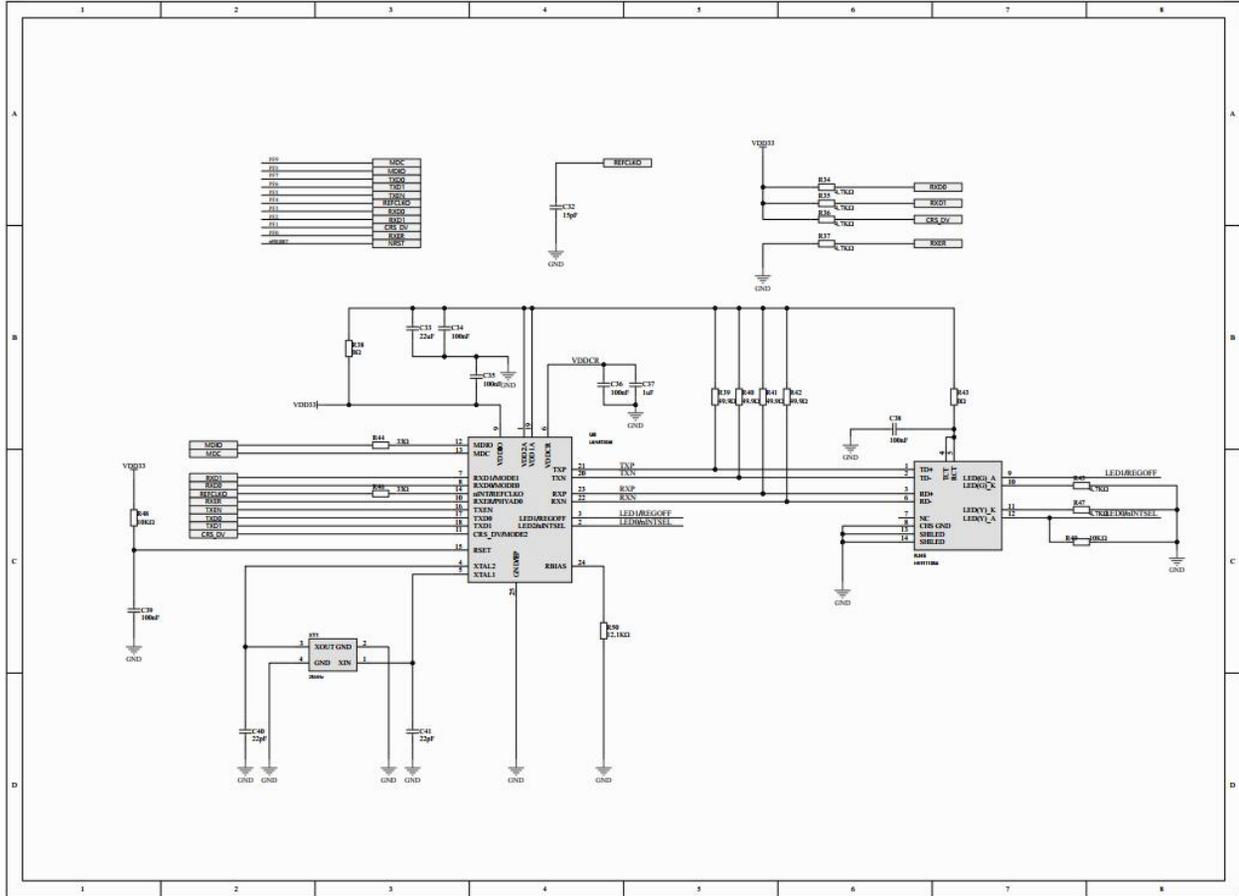


Figure 5-8 Ethernet connector Schematic

5.9 RS485 and CAN Schematic

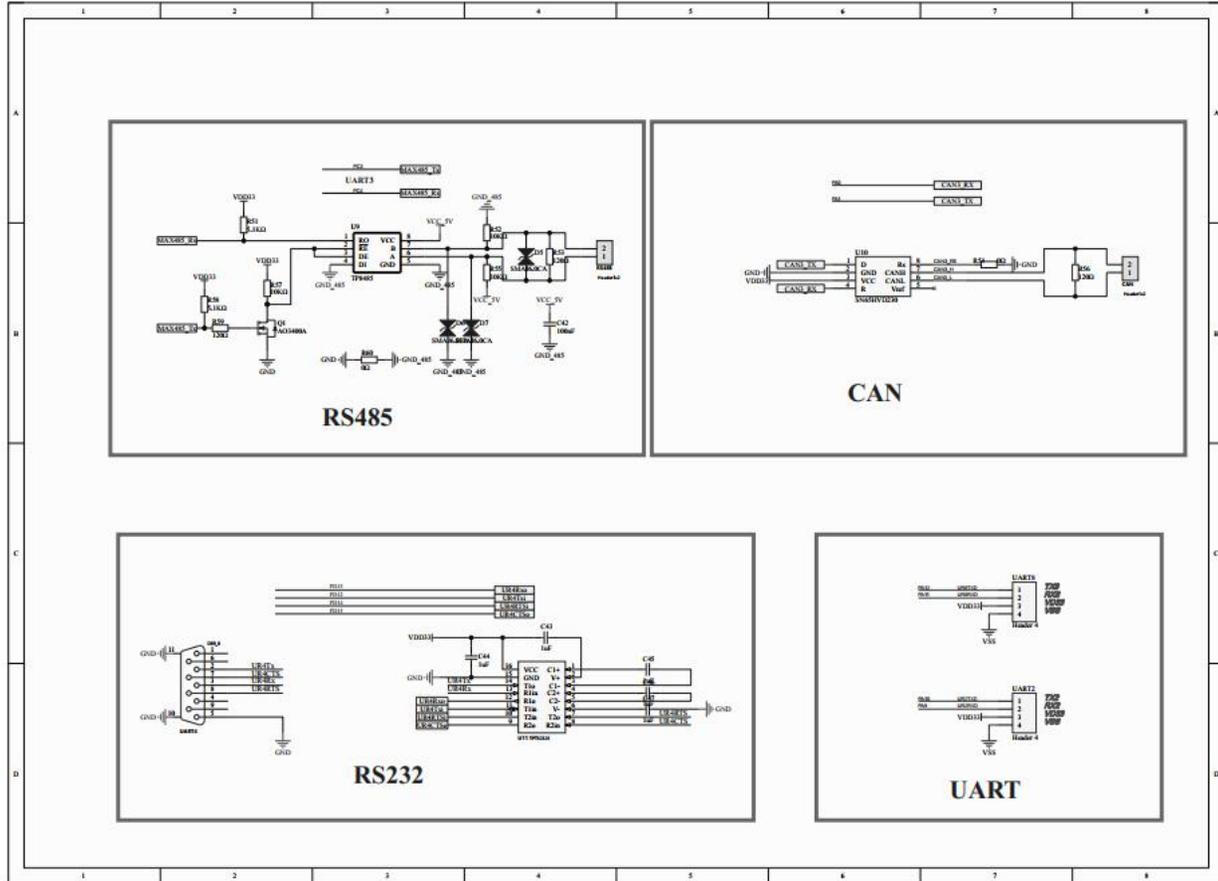


Figure 5-9 RS485 and CAN Schematic

5.10 USB Hub

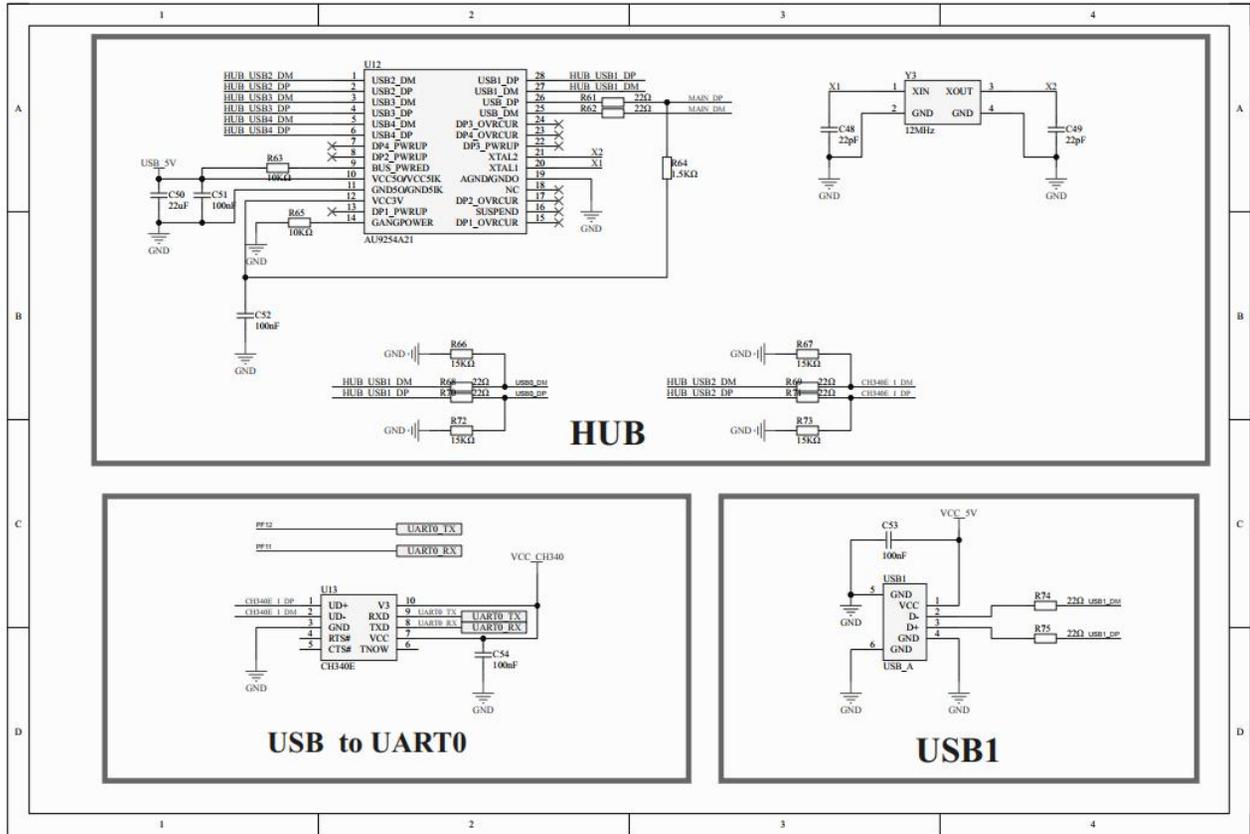


Figure 5-10 USB Hub

5.11 PCB Placement

Figure 5-11 Front PCB Placement

6 REVISION HISTORY

Date	Revision	Description
2021.08.26	1.00	1. Initial version